

## Diffusion Models - Applications

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The breadth of scientific applications — from drug discovery to atmospheric modeling, from protein design to seismic inversion — demonstrates that the diffusion paradigm is not merely an image synthesis technique but a general framework for probabilistic inverse problems in science and engineering: wherever one seeks to sample from a complex posterior distribution conditioned on observed data, diffusion models offer a principled and scalable solution.

### Drug Discovery

Diffusion models have been adapted from image synthesis to the generation of molecular structures by defining the forward process on three-dimensional atomic coordinates and bond types.

DiffSBDD (*Schneuing et al., 2022*) and DiffDock (*Corso et al., 2022*) apply diffusion over the SE(3) group — the special Euclidean group of rigid-body motions in 3D space — to generate ligand poses docked into protein binding sites. The forward process adds translational and rotational noise:

$$q(\mathbf{r}_t | \mathbf{r}_{t-1}) = \mathcal{N}(\mathbf{r}_t; \sqrt{1 - \beta_t} \mathbf{r}_{t-1}, \beta_t \mathbf{I}), \quad q(\mathbf{R}_t | \mathbf{R}_{t-1}) = \text{IGSO}(3)(\mathbf{R}_{t-1}, \sigma_t^2)$$

where  $\mathbf{r}$  denotes position (translation) and  $\mathbf{R}$  denotes orientation (rotation), with the Isotropic Gaussian distribution on SO(3) used for rotational noise. Applications include de novo drug design, generating candidate molecules with desired binding affinity and pharmacological properties — a domain where experimental screening of  $10^{60}$  possible drug-like molecules is physically infeasible.

### Weather Forecasting and Climate Emulation

GenCast (*Price et al., 2023*, Google DeepMind) and CorrDiff (*Mardani et al., 2023*, NVIDIA) apply diffusion models to ensemble weather forecasting — generating probabilistic distributions over future atmospheric states that capture forecast uncertainty.

Traditional numerical weather prediction (NWP) models solve the *Navier–Stokes* equations discretized on a global grid, requiring supercomputer resources. Diffusion-based emulators treat the atmospheric state (temperature, wind, pressure fields) as images and model the conditional distribution:

$$p_\theta(\mathbf{x}_{t+\Delta t} | \mathbf{x}_t)$$

where  $\mathbf{x}_t$  is the atmospheric state at time  $t$  encoded as a multi-channel field on a global grid. GenCast achieves ensemble forecast skill exceeding ECMWF's (European Centre for Medium-Range Weather Forecasts) ENS system at 15-day horizons, at a fraction of the computational cost.

### Medical Imaging

Diffusion models address critical challenges in medical imaging, including data scarcity, privacy constraints on real patient data, and artifact removal.

Reconstruction from undersampled MRI (*Song et al., 2021*): MRI acquisition time is proportional to the number of k-space measurements. Diffusion models enable compressed sensing reconstruction: given undersampled *Fourier* measurements  $\mathbf{y} = \mathcal{A}\mathbf{x} + \boldsymbol{\eta}$  (where  $\mathcal{A}$  is a partial *Fourier* operator), the

posterior  $p(\mathbf{x} | \mathbf{y})$  is approximated by conditioning the reverse diffusion process on the data consistency term:

$$\nabla_{\mathbf{x}_t} \log p(\mathbf{x}_t | \mathbf{y}) = \nabla_{\mathbf{x}_t} \log p(\mathbf{x}_t) + \nabla_{\mathbf{x}_t} \log p(\mathbf{y} | \mathbf{x}_t)$$

This enables 4–8× acceleration of MRI scans with diagnostic-quality reconstructions, directly translating to reduced patient burden and scanner throughput improvement.

Anomaly detection (*Wolleb et al., 2022*): Diffusion models trained on healthy brain MRI can detect pathological structures by measuring the deviation between a patient scan and its diffusion-based reconstruction — pathological regions that violate the learned healthy distribution appear as high residual areas.

### Crystal Structure Prediction

CDVAE (*Xie et al., 2022*) and DiffCSP (*Jiao et al., 2023*) apply diffusion to crystal structure prediction — determining the stable three-dimensional arrangement of atoms in a material given its chemical composition. The forward process noises both the fractional atomic coordinates and the lattice parameters (unit cell lengths and angles):

$$\mathcal{L}(\mathbf{a}, \mathbf{b}, \mathbf{c}, \alpha, \beta, \gamma) \longrightarrow \mathcal{L}_T \approx \mathcal{N}(\bar{\mathcal{L}}, \sigma_L^2 \mathbf{I})$$

Applications include predicting novel battery electrode materials, high-temperature superconductors, and catalysts for  $CO_2$  reduction — materials synthesis problems of enormous commercial and environmental relevance.

### Protein Structure and Dynamics

RFdiffusion (*Watson et al., 2023, Nature*) applies diffusion over backbone dihedral angles and Cartesian coordinates in  $SE(3)$  to de novo protein design — generating protein backbone structures with desired functional properties. The reverse process generates structures conditioned on a target binding site:

$$p_{\theta}(\mathbf{x}_{\text{protein}} | \mathbf{x}_{\text{target}})$$

Experimental validation demonstrated that designed proteins bound their targets with affinities competitive with naturally evolved antibodies — a landmark result illustrating that diffusion models can discover functional structures in a combinatorially vast design space ( $20^{100}$  possible 100-residue proteins).

### Seismic Imaging

In geophysics, Full Waveform Inversion (FWI) reconstructs subsurface velocity models  $\mathbf{m}$  from observed seismic data  $\mathbf{d}$ , solving the ill-posed inverse problem:

$$\min_{\mathbf{m}} \|\mathcal{F}(\mathbf{m}) - \mathbf{d}\|^2 + \mathcal{R}(\mathbf{m})$$

where  $\mathcal{F}$  is the wave-equation forward operator. Diffusion models serve as learned regularizers  $\mathcal{R}(\mathbf{m})$  (*Gao & Alkhalifah, 2023*), encoding realistic prior distributions over subsurface geology and enabling

probabilistic uncertainty quantification in reservoir characterization — directly impacting oil and gas production decisions and  $CO_2$  storage site selection.

### Autonomous Systems and Robotics

Diffusion Policy (*Chi et al.*, 2023, RSS) applies diffusion models to robot learning from demonstration, treating action sequences as generative targets:

$$p_{\theta}(\mathbf{a}_{t:t+H} \mid \mathbf{o}_{t-k:t})$$

where  $\mathbf{a}$  are robot actions,  $\mathbf{o}$  are observations, and  $H$  is the prediction horizon. By modeling the multi-modal distribution of expert behavior — humans demonstrating a task may approach it in several qualitatively different ways — diffusion policies significantly outperform regression-based imitation learning on dexterous manipulation tasks.

### Limitations and Research Frontiers

The sequential nature of the reverse process remains a bottleneck. While DDIM and DPM-Solver reduce steps to  $\mathcal{O}(10-20)$ , each step requires a full U-Net forward pass. Consistency Models (*Song et al.*, 2023) attempt to learn a direct mapping from noise to data in one step by enforcing a self-consistency property:

$$\mathbf{f}_{\theta}(\mathbf{x}_t, t) = \mathbf{f}_{\theta}(\mathbf{x}_{t'}, t') \quad \forall t, t' \text{ on the same ODE trajectory}$$

Diffusion models empirically exhibit excellent mode coverage — they produce diverse samples across the full data distribution. However, classifier-free guidance, while improving individual sample quality, reduces diversity (a manifestation of the fidelity–diversity trade-off encoded in the Precision-Recall framework).

Text-to-image models exhibit semantic hallucination: failure to accurately render object attributes, spatial relationships, or numerical quantities specified in prompts. The CLIP text encoder's limited capacity to encode compositional semantics is a known failure mode under active investigation.

The standard *Gaussian* diffusion framework applies to continuous data. Extension to discrete data (text, molecular graphs) requires non-Gaussian forward processes. Multinomial diffusion (*Austin et al.*, 2021) and absorbing diffusion processes define forward corruption via categorical noise:

$$q(\mathbf{x}_t \mid \mathbf{x}_0) = \text{Cat}(\mathbf{x}_t; \mathbf{x}_0 \bar{\mathbf{Q}}_t)$$

where  $\bar{\mathbf{Q}}_t$  is a cumulative transition matrix over the token vocabulary.